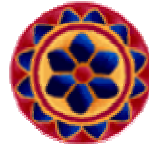


Seeding Up Genomic Data Mining via Symbolic Manipulation of Boolean Functions

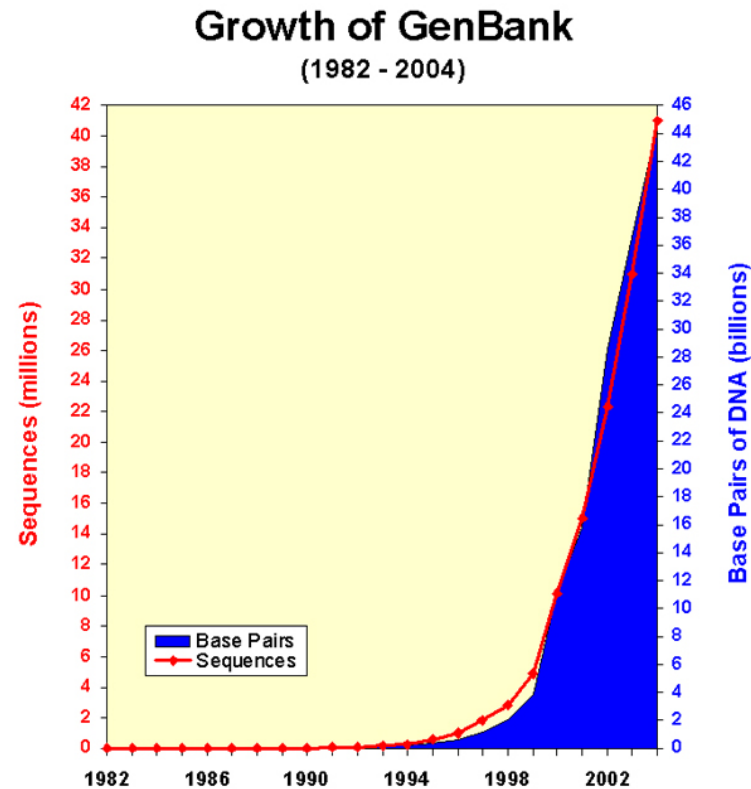


Sungroh Yoon

Computer Systems Laboratory
Stanford University

- **Introduction**
- Problem formulation
- Algorithm description
- Applications

Explosion of Genomic Data

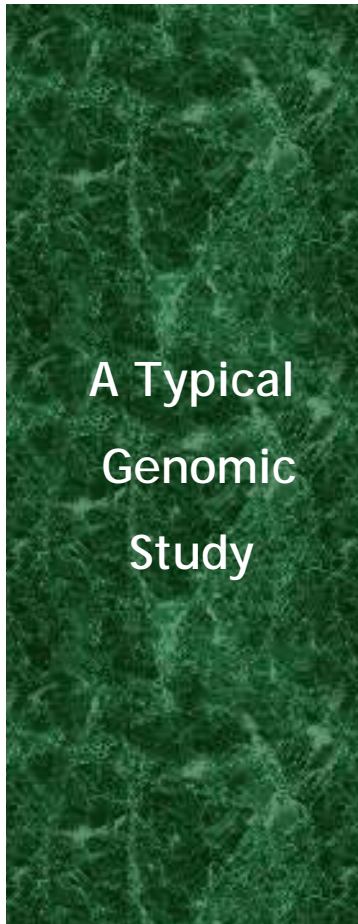


- <http://www.ncbi.nlm.nih.gov/Genbank/genbankstats.html>

Challenges in Genomic Data Analysis

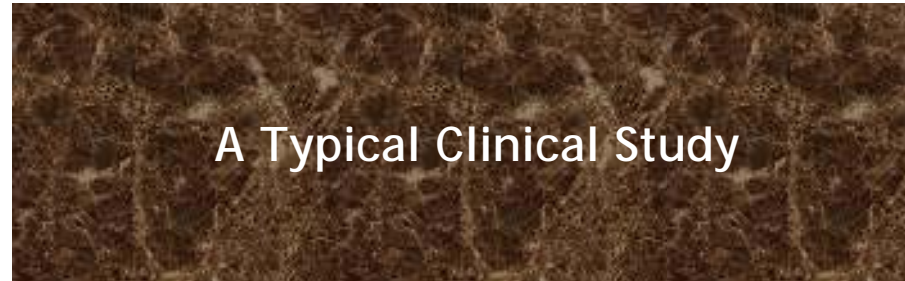
Cases (10's - 100's)

Variables (10,000's - 100,000's)



Variables (10's - 100's)

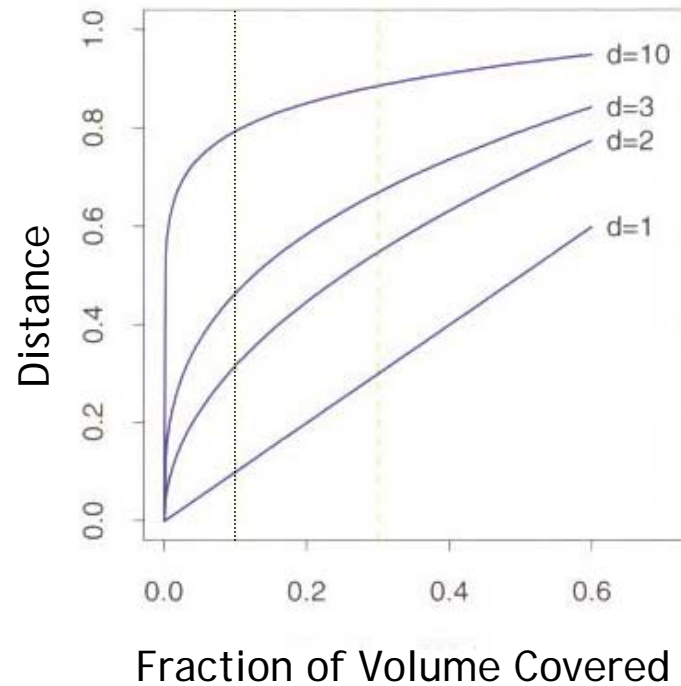
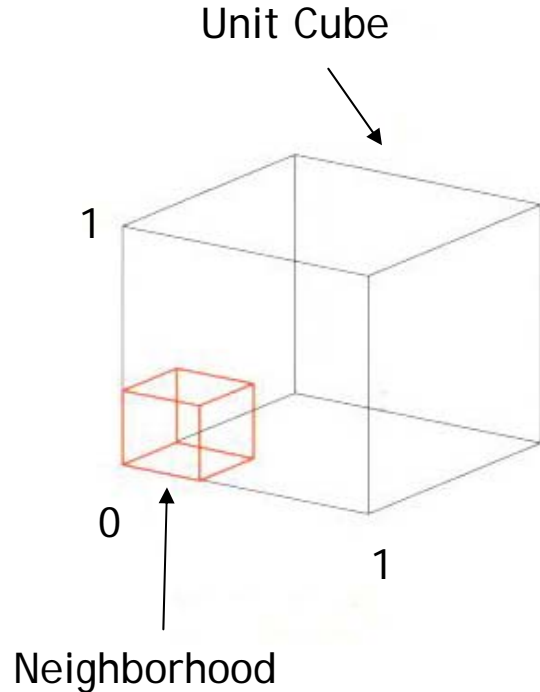
Cases (1,000's - 1,000,000's)



- Underdetermined system

Challenges in Genomic Data Analysis

- The curse of dimensionality
- Example: k-NN

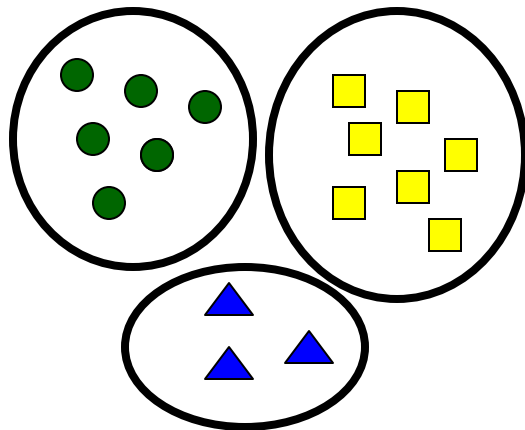


Hastie et al., *The Elements of Statistical Learning*, 2001

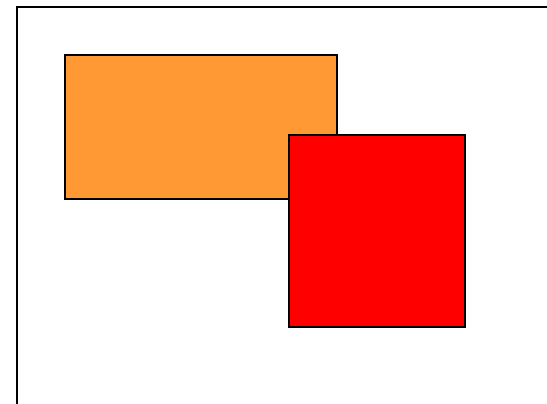
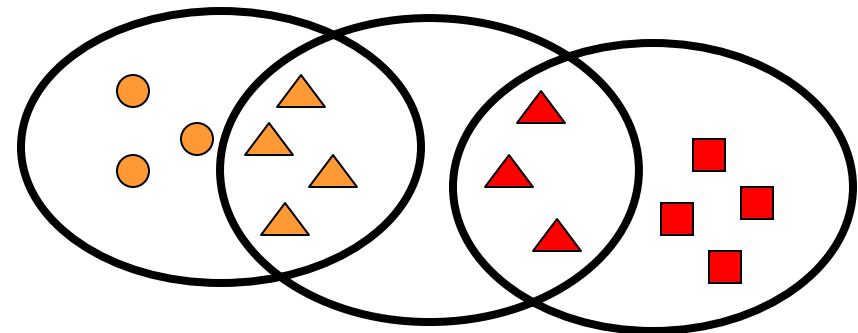
- Idea
 - Focus on subsets of data
 - Simultaneous clustering of objects and features
- Subspace clustering + 2-way clustering
- Allow overlaps

Clustering vs. biclustering

- Clustering



- Biclustering



- **Pros**

- Can handle the curse better
 - Some desirable statistical properties reported
- Finer, more localized analysis
 - Samples/experimental conditions can be diverse
- Overlaps allowed
 - Genes have multiple functions

- **Cons**

- Reliable statistics needed for validation
- Inherently intractable problem

- Mathematical characterization of the biclustering problem
- An exact and scalable algorithm
 - Leveraged by symbolic manipulation of Boolean functions
- Applications
 - DNA microarray data analysis
 - Predicting gene regulatory modules
 - Correlating clinical parameters with genes

- Introduction
- **Problem formulation**
 - Homogeneous biclusters
 - 3 types of homogeneous biclusters
- Algorithm description
- Applications

- Input
 - $A=(R,C)$, a matrix of real numbers
 - D , a specific condition giving some semantics
- Output
 - Biclusters $B=(I,J)$
 - Submatrices of A
 - Satisfy the condition D
 - Can overlap with each other

- D: the values on each row are constant

1.0	1.0	1.0	1.0
1.0	1.0	1.0	3.0
2.0	2.0	3.0	2.0
3.0	3.0	2.0	3.0

1.0	1.0	1.0
1.0	1.0	1.0

1.0	1.0
1.0	1.0
2.0	2.0
3.0	3.0

1.0	1.0	1.0
2.0	2.0	2.0
3.0	3.0	3.0

- Given matrix A and condition D
- Suppose B is a bicluster in A under D
- B is called *homogeneous* if
 - Any sub-bicluster of B also satisfies D
- Example
 - D : the values on each row are constant

1.0	1.0	1.0	1.0
1.0	1.0	1.0	3.0
2.0	2.0	3.0	2.0
3.0	3.0	2.0	3.0



1.0	1.0	1.0
2.0	2.0	2.0
3.0	3.0	3.0

- **Desirable properties**
 - More intuitive
 - Allow us to devise a more efficient algorithm
 - Optimal substructure for dynamic programming
 - Can be statistically better
 - Smaller residues (in ANOVA theory)
- **Many examples in the literature**
 - xMOTIF, δ -valid kj pattern, GEMS
 - OPSM, OP-cluster
 - δ -pCluster

- Applicable to finding homogeneous biclusters of any definition
- Three specific examples
 - Type 1
 - Biclusters with constant values on rows
 - Type 2
 - Biclusters in which the order of values on each row is preserved
 - Type 3
 - Biclusters with coherent values

- **Definition: RANGE**
 - $\text{RANGE}(\langle 1,2,3,4,5 \rangle) = 4$
- **Type 1 homogeneous bicluster**
 - A submatrix (I,J)
 - Given $\tau \geq 0$, $\forall i \in I, \text{RANGE}(\{a_{ij} | \forall j \in J\}) \leq \tau$.
- **Related examples**
 - xMOTIF, δ -valid kj pattern, GEMS

$$\tau = 0.5$$

1.4	1.0	1.2	1.7
3.0	3.1	3.3	3.0
2.0	1.9	2.4	2.5
3.2	3.7	2.0	3.0

$$1.4 - 1.0 = 0.4 \leq 0.5$$

$$3.3 - 3.0 = 0.3 \leq 0.5$$

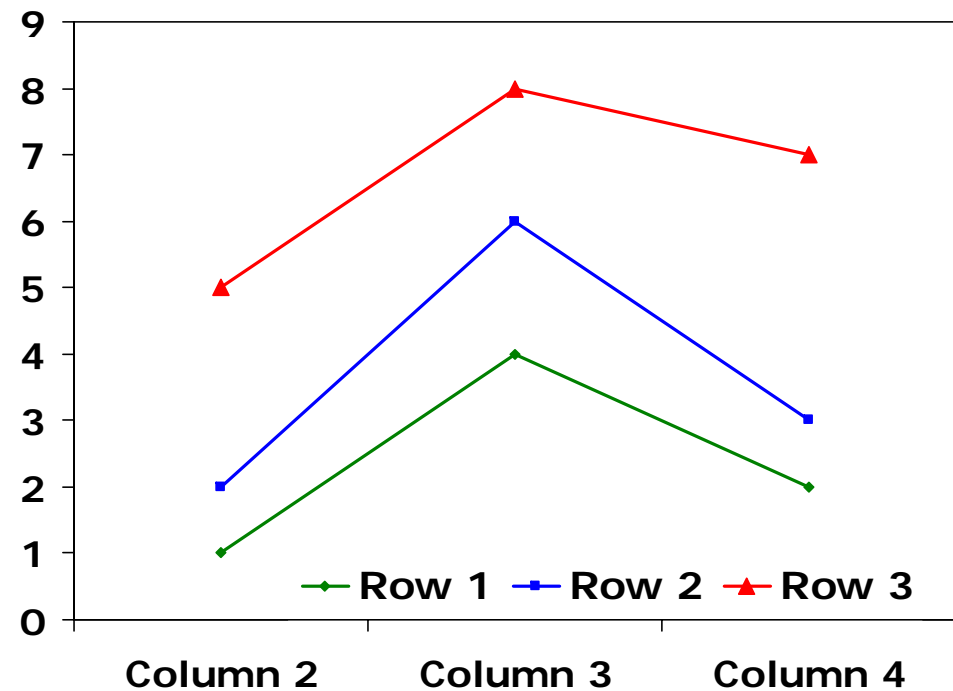
$$2.4 - 1.9 = 0.5 \leq 0.5$$

- Given a data matrix $A = (R, C)$
 - Let $J \star C$ be a set of size $s \geq 2$
 - Let $\pi = (p_1, p_2, \dots, p_s)$ be a linear ordering of J
- Type 2 homogeneous bicluster
 - A submatrix (I, J)
 - The order of the values on rows are preserved
 - That is, $i \in I, a_{ip_1} > a_{ip_2} > \dots > a_{ip_s}$.
- Related examples
 - OPSM, OP-cluster

- $R = \{1, 2, 3\}$, $C = \{1, 2, 3, 4\}$

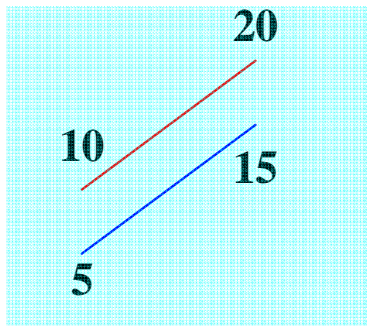
	1	2	3	4
1	3.0	1.0	4.0	2.0
2	7.0	2.0	6.0	3.0
3	6.0	5.0	8.0	7.0

- $i \in \{1, 2, 3\}$,
 $a_{i3} > a_{i4} > a_{i2}$.

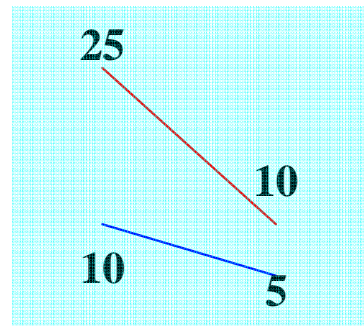


- Measure of coherence
 - Defined over 2 ● 2 matrices

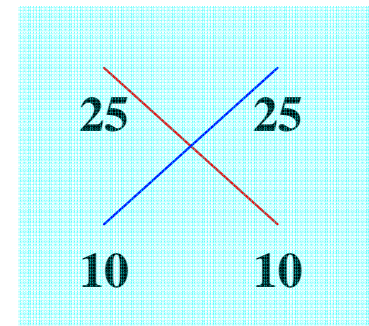
$$\begin{aligned} pScore \left(\begin{bmatrix} x_1 & x_2 \\ y_1 & y_2 \end{bmatrix} \right) &= |(x_1 - y_1) - (x_2 - y_2)| \\ &= |(x_1 - x_2) - (y_1 - y_2)| \end{aligned}$$



pScore = 0



pScore = 10

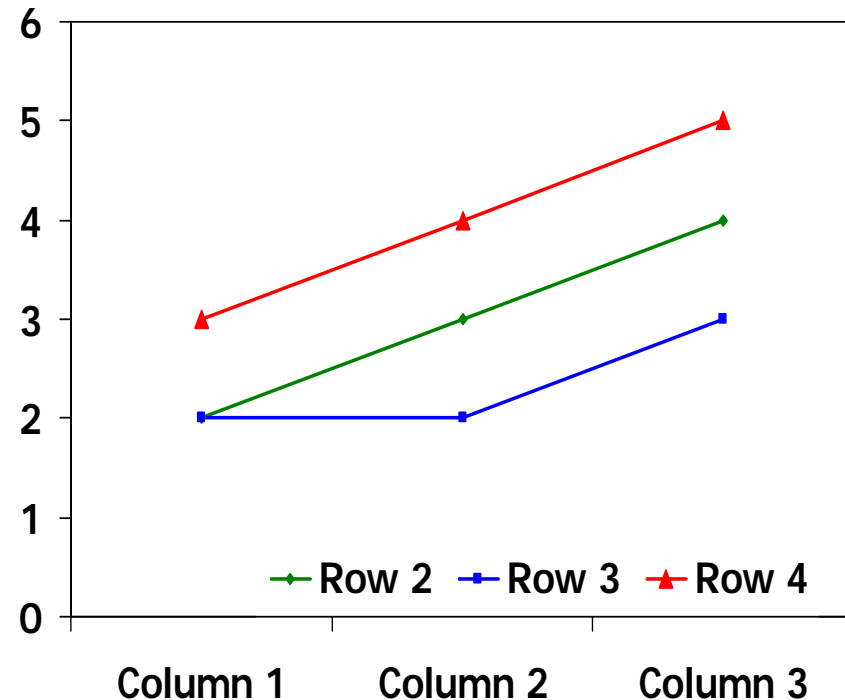


pScore = 30

- Type 3 homogeneous bicluster
 - A submatrix (I,J)
 - Given $\tau \geq 0$
 - Every 2×2 submatrix X has $\text{pScore}(X) \leq \tau$
- Related examples
 - δ -bicluster, FLOC cluster, δ -pCluster

- $\tau = 1$

6.0	9.0	2.0	5.0
2.0	3.0	4.0	3.0
2.0	2.0	3.0	6.0
3.0	4.0	5.0	2.0



$$pScore \left(\begin{bmatrix} 2 & 3 \\ 2 & 2 \end{bmatrix} \right) = |(2 - 2) - (3 - 2)| = 1 \leq \tau$$

- Given an input data matrix $A = (R, C)$ and type $t \in \{Type1, Type2, Type3\}$
- The problem of biclustering is to find all maximal bi-clusters of type t appearing in A
 - A bicluster is *maximal* if it is not contained by other biclusters

- Introduction
- Problem formulation
- **Algorithm description**
 - Overview
 - Step 1: finding seeds
 - Step 2: deriving biclusters from seeds
- Applications

Two-step process

STEP 1

- User-specified front-end
- AD Converter
- Generate "seeds"
- Determines bicluster type

Type 1

Type 2

Type 3

xMOTIF

δ valid kj pattern

GEMS

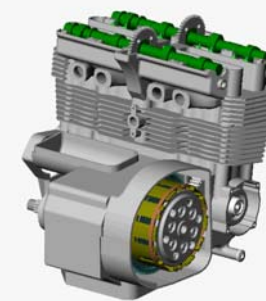
OPSM

OP-cluster

:
:
:

STEP 2

- Powerful biclustering engine
- DSP
- Derive biclusters from seeds
- Common for all bicluster type

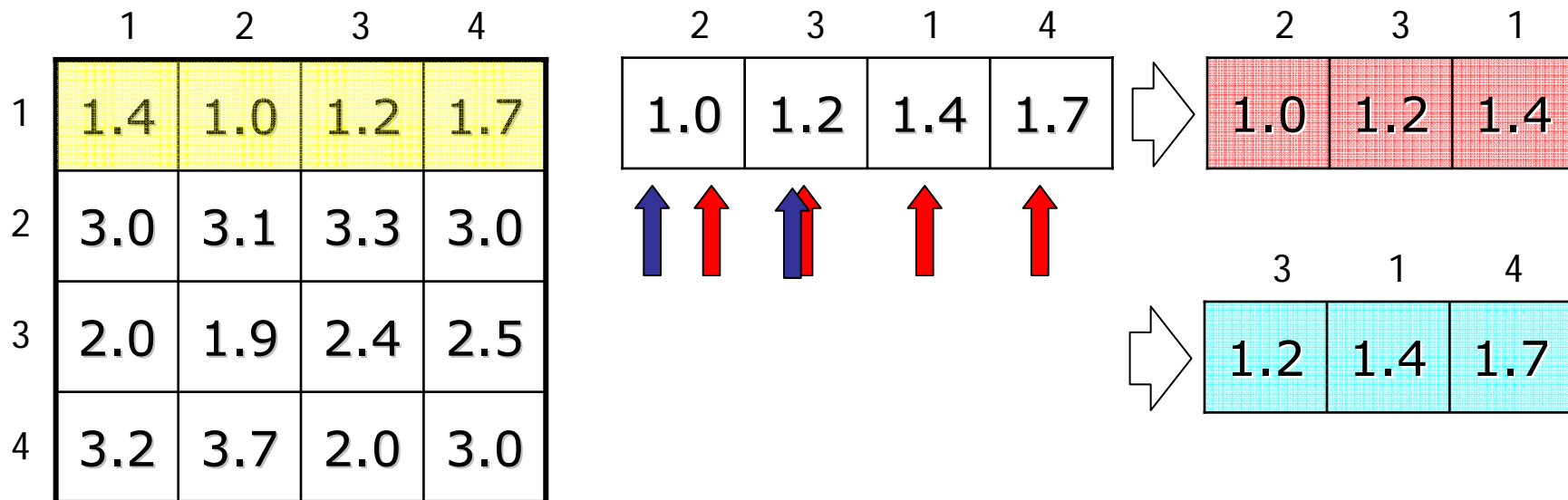


- Biclusters of the minimum number of rows

Type 1	(1 x k) matrix
Type 2	(2 x k) matrix
Type 3	(2 x k) matrix

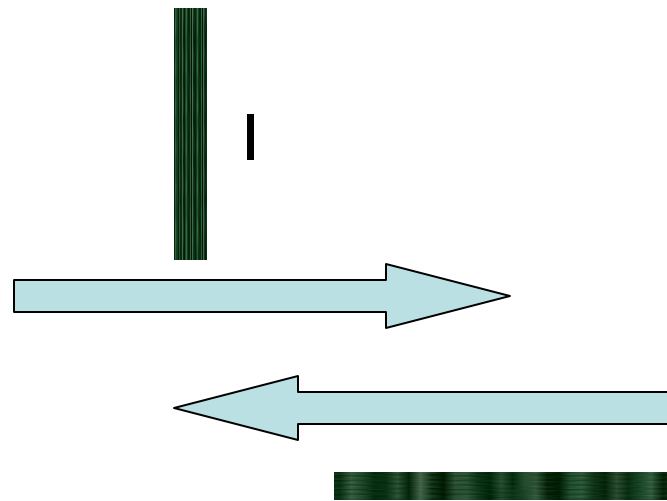
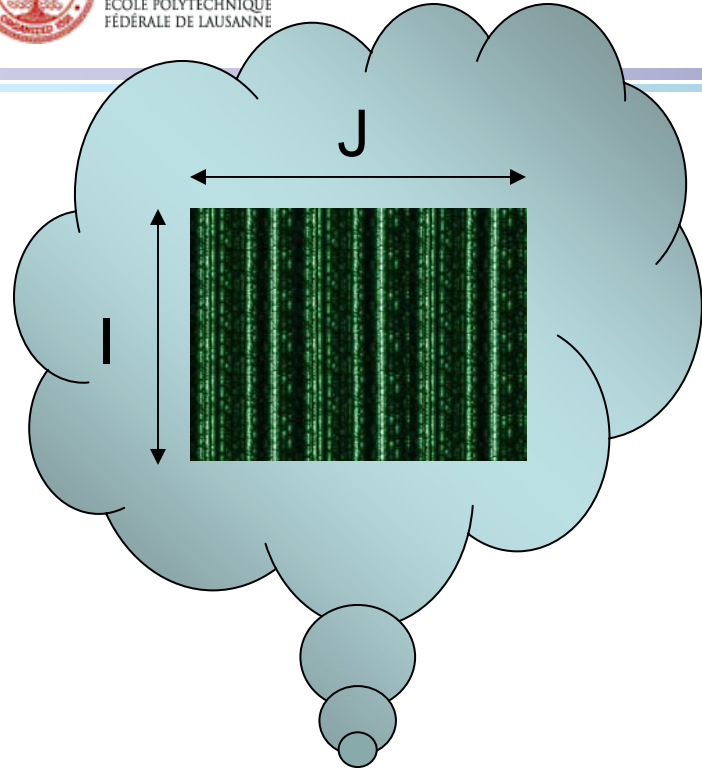
- Finds only maximal seeds
- Polynomial-time algorithm

- Type 1 seed: a row vector with near constant values
- Example ($\tau = 0.5$)



- Two seeds for row 1
 - ($\{1\}, \{1, 2, 3\}$)
 - ($\{1\}, \{1, 3, 4\}$)

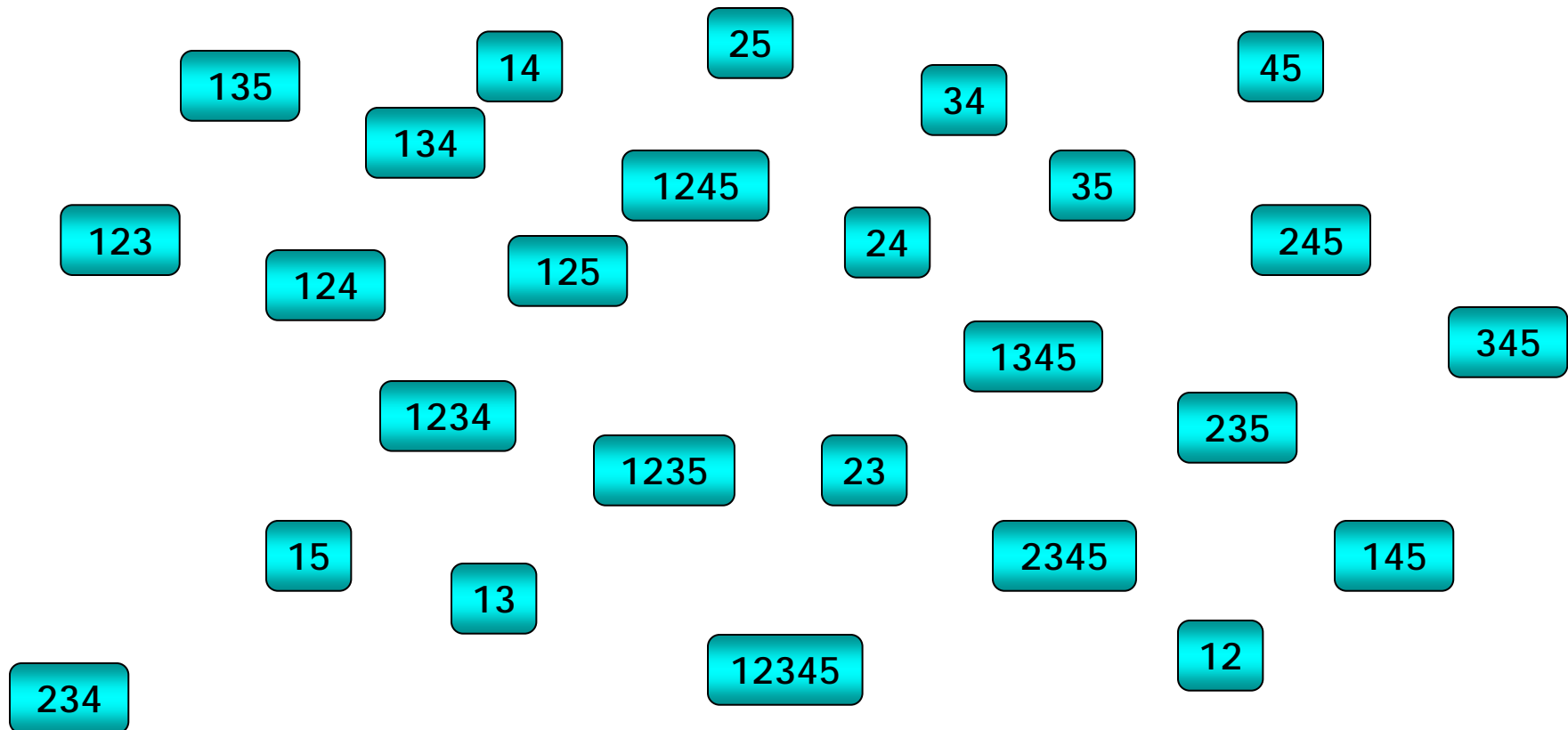
Step 2: Big Picture



$$\left. \begin{array}{l} \text{[Matrix-style image]} \\ \text{[Image of Neo]} \end{array} \right\} \begin{array}{l} J \\ J \end{array} \cong \mathcal{J}(I)$$

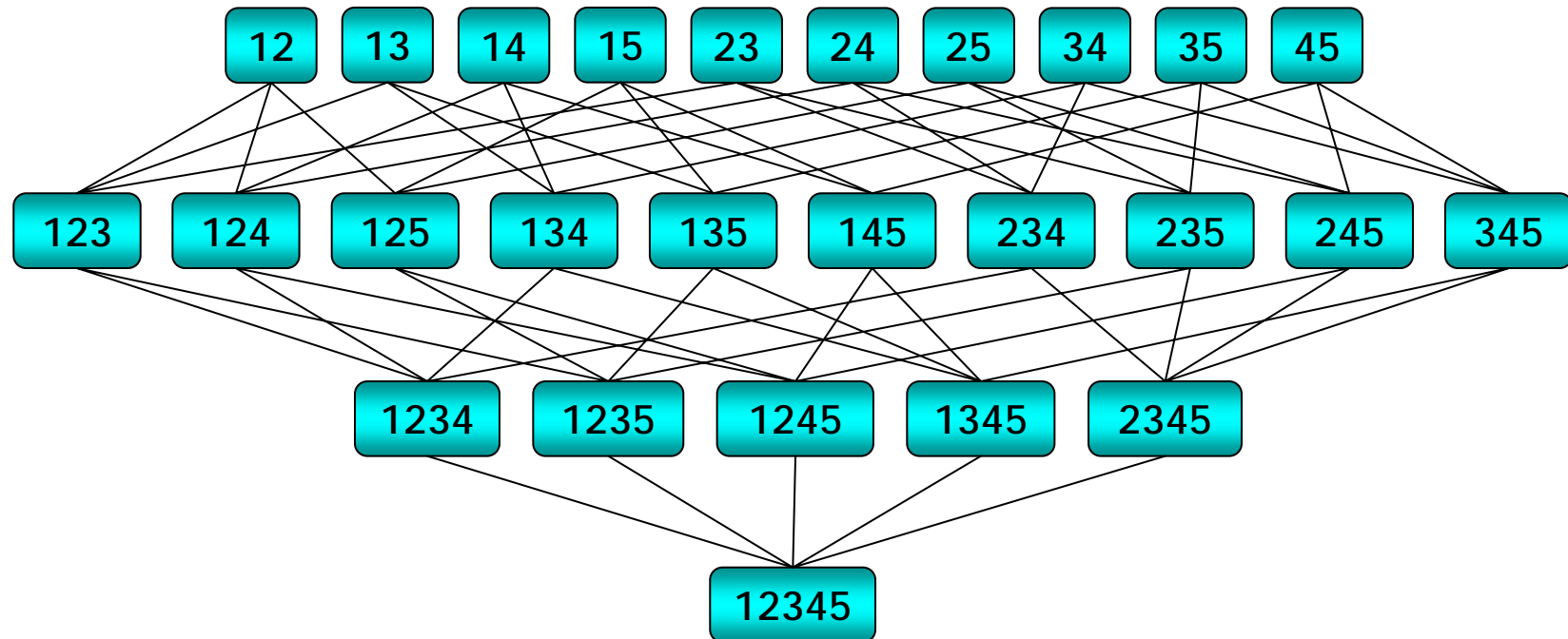


$$I \in 2^R, R = \{1, 2, 3, 4, 5\}$$



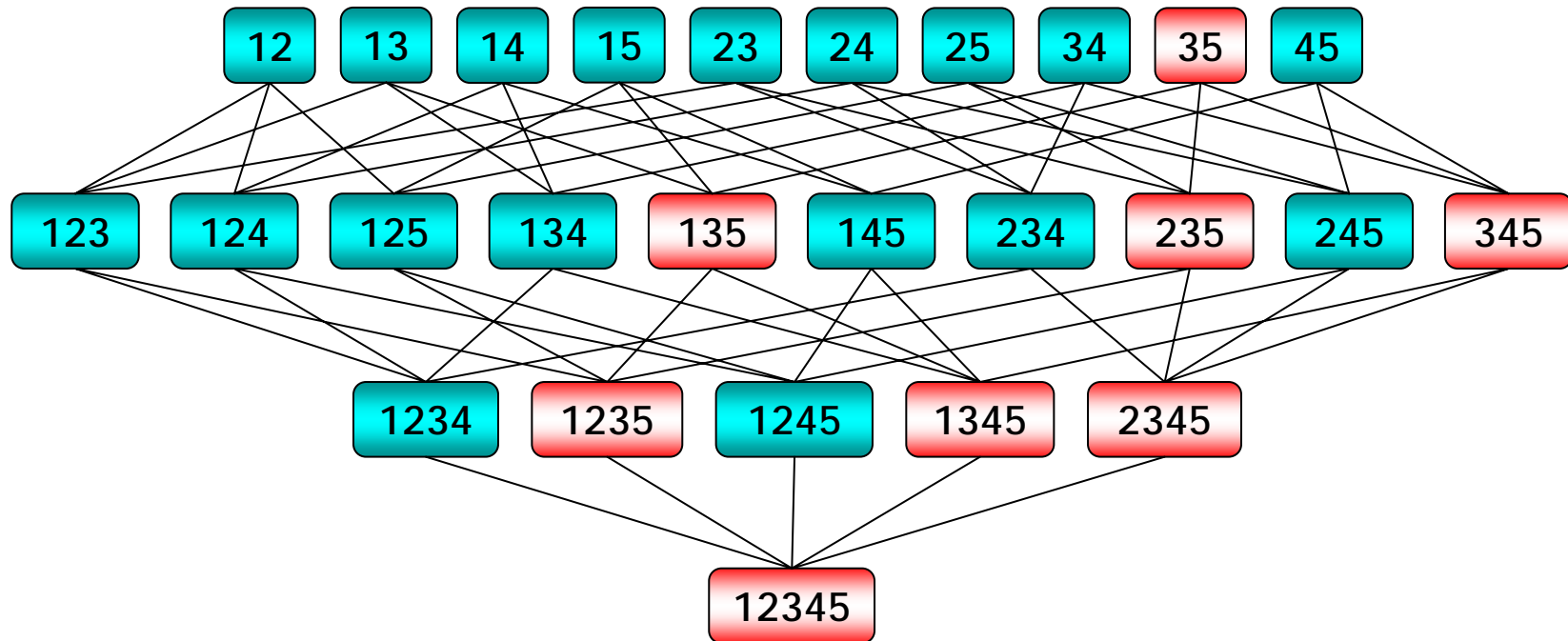


- Lattice for $I \in 2^R$, $R = \{1, 2, 3, 4, 5\}$



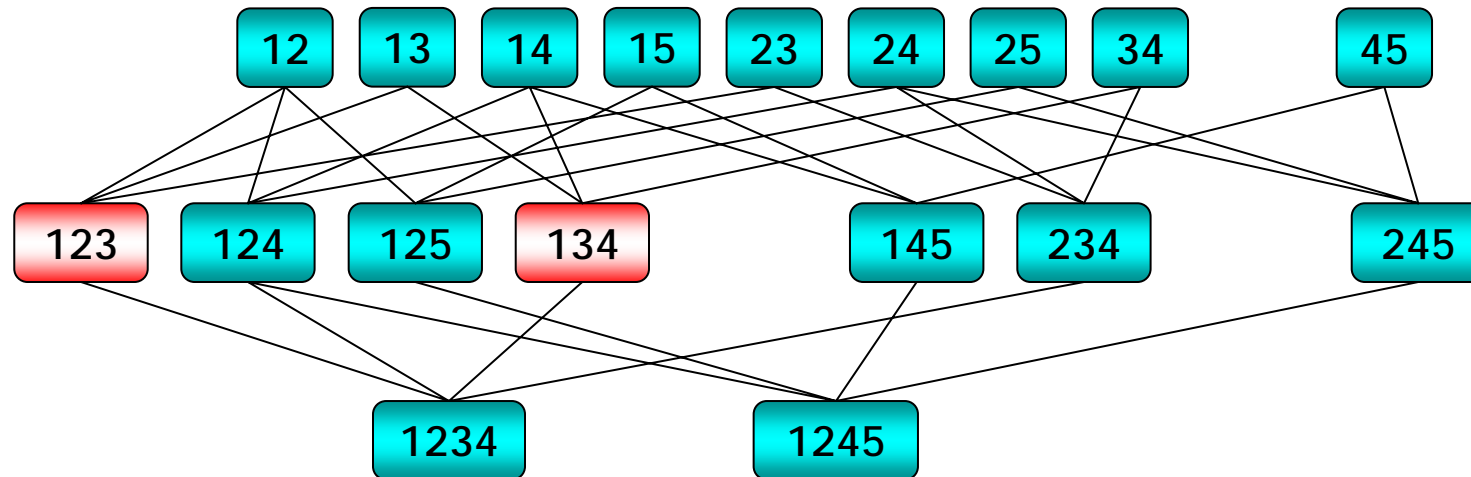


- Suppose that $\mathcal{J}(\{3, 5\}) = \emptyset$





- Also, $\mathcal{J}(\{1, 2, 3\}) = \mathcal{J}(\{1, 3, 4\}) = \emptyset$

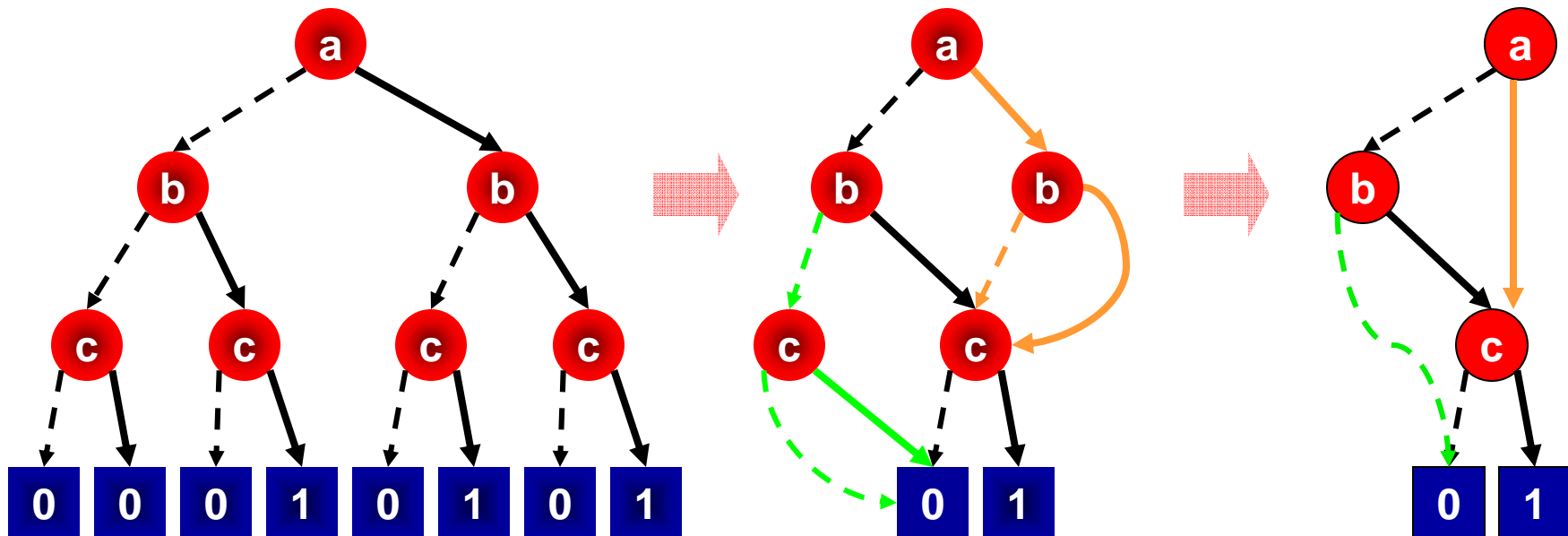




- <http://citeseer.ist.psu.edu/source.html>
(as of July 2004)
1. *Graph-Based Algorithms for Boolean Function Manipulation* - Bryant (1986)
 2. *Optimization by Simulated Annealing* - Kirkpatrick, Gelatt, Jr., Vecchi (1983)
 3. *A Method for Obtaining Digital Signatures and Public-Key Cryptosystems* - Rivest, Shamir, Adleman (1978)
 14. *Fast Algorithms for Mining Association Rules* - Agrawal, Srikant (1994)
 15. *The Java Language Specification* - Gosling, Joy, Steele (1996)

Reduced Ordered BDDs (Bryant)

- Ordered
- Reduced
 - 1. Merge equivalent sub-trees
 - 2. Remove nodes with identical children



Zero-suppressed BDDs (Minato)

- Optimized for sets of combinations

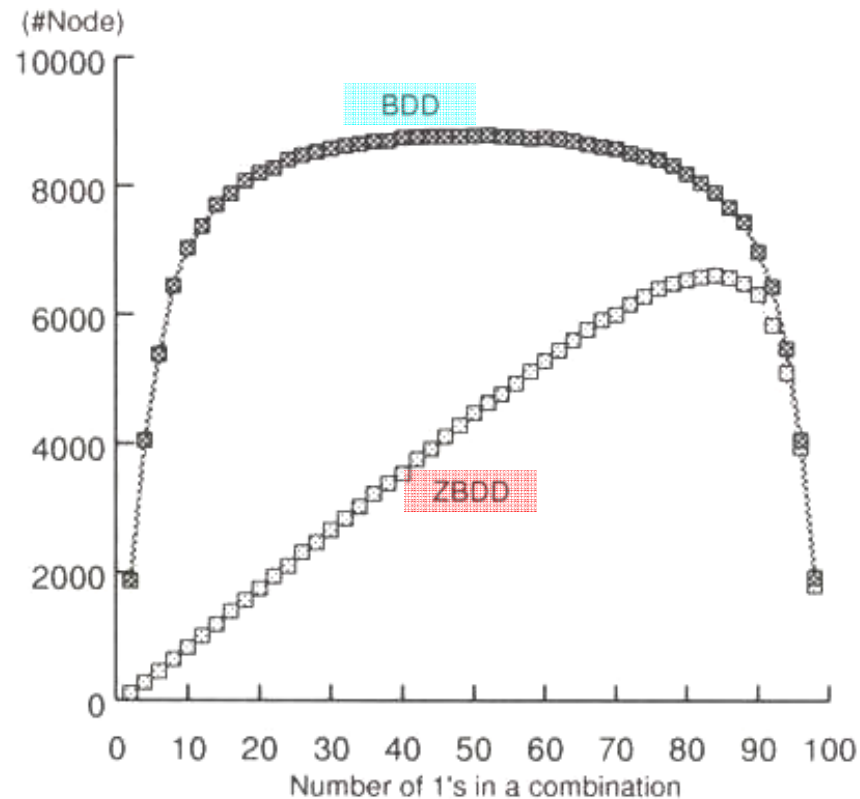


Figure 6.6 Comparison of BDDs and ZBDDs.

S. Minato, *BDDs and Applications for VLSI CAD*, Kluwer, 1996

- Given $A = (R, C)$, an input data matrix, and \mathcal{D} , a specific definition of a bicluster, $\mathfrak{R}_{\mathcal{D}}$ is a binary relation on $2^R \times 2^C$:

$$\mathfrak{R}_{\mathcal{D}} = \{(I, J) \mid \text{The pair } (I, J) \text{ is a bicluster in } A \text{ under } \mathcal{D}\}.$$

- Given matrix $A = (R, C)$, \mathcal{J} is a function that maps $I \in 2^R$ to the image $\mathcal{J}(I)$, where

$$\mathcal{J}(I) = \{J \in 2^C \mid (I, J) \in \mathfrak{R}_{\mathcal{D}} \text{ and } \nexists J' \supset J \text{ s.t. } (I, J') \in \mathfrak{R}_{\mathcal{D}}\}.$$



- $\tau=0.5, t=1$

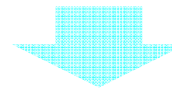
	1	2	3	4
1	1.4	1.0	1.2	1.7
2	3.0	3.1	3.3	3.0
3	2.0	1.9	2.4	2.5
4	3.2	3.7	2.0	3.0

	1	2	3
1	1.4	1.0	1.2

$J(\{1\})$

	1	2	3	4
2	3.0	3.1	3.3	3.0

$J(\{2\})$



	1	2	3
1	1.4	1.0	1.2
2	3.0	3.1	3.3

$$J(\{1, 2\}) = J(\{1\}) \cap J(\{2\})$$

- $I = \{1, 2\}$
- $J = ?$

- $\tau=1, t=3$

	1	2	3	4
1	6.0	9.0	2.0	5.0
2	2.0	3.0	5.0	6.0
3	2.0	2.0	3.0	4.0
4	1.0	0.0	1.0	2.0

	1	2	3	4
2	2.0	3.0	5.0	6.0
3	2.0	2.0	3.0	4.0

$J(\{2, 3\})$

	2	3	4
2	3.0	5.0	6.0
4	0.0	1.0	2.0

$J(\{2, 4\})$

	1	2	3	4
3	2.0	2.0	3.0	4.0
4	1.0	0.0	1.0	2.0

$J(\{3, 4\})$

- $I = \{2, 3, 4\}$

- $J = ?$

$$J(\{2, 3, 4\}) = J(\{2, 3\}) \cap J(\{2, 4\}) \cap J(\{3, 4\})$$

- The *pairwise intersection* of two sets of sets \mathcal{A} and \mathcal{B} , denoted by $\mathcal{A} \otimes \mathcal{B}$, is defined as

$$\mathcal{A} \otimes \mathcal{B} = \{I \mid I = A \cap B, \forall A \in \mathcal{A} \text{ and } \forall B \in \mathcal{B}, \text{ and } I \text{ is maximal}\}.$$

- $\{\{0, 1, 2\}, \{2, 3, 4\}\} \otimes \{\{0, 2\}, \{4, 5\}\} = \{\{0, 2\}, \{4\}\}$
- The pairwise intersection of the n sets of sets $\mathcal{A}_1, \mathcal{A}_2, \dots, \mathcal{A}_n$ is denoted by

$$\mathcal{A}_1 \otimes \mathcal{A}_2 \otimes \dots \otimes \mathcal{A}_n = \bigotimes_{i=1}^n \mathcal{A}_i.$$

- Let \mathcal{J}_1 , \mathcal{J}_2 , and \mathcal{J}_3 denote the function \mathcal{J} for Types 1, 2, and 3, respectively.
- Given input data $A = (R, C)$, the image of $I \in 2^R$, or $\mathcal{J}(I)$, can be represented as follows.

- When the set I has only one or two elements:

$$\mathcal{J}_1(\{r\}) = \{J \mid \text{The pair } (\{r\}, J) \text{ is a Type 1 seed for row } r \in R\}$$

$$\mathcal{J}_2(\{q, r\}) = \{J \mid \text{The pair } (\{q, r\}, J) \text{ is a Type 2 seed for rows } q, r \in R\}$$

$$\mathcal{J}_3(\{q, r\}) = \{J \mid \text{The pair } (\{q, r\}, J) \text{ is a Type 3 seed for rows } q, r \in R\}$$

- Otherwise:

$$\mathcal{J}_1(I) = \bigotimes_{\forall i \in I} \mathcal{J}_1(\{i\})$$

$$\mathcal{J}_2(I) = \bigotimes_{\forall E \in \text{cover}(I)} \mathcal{J}_2(E)$$

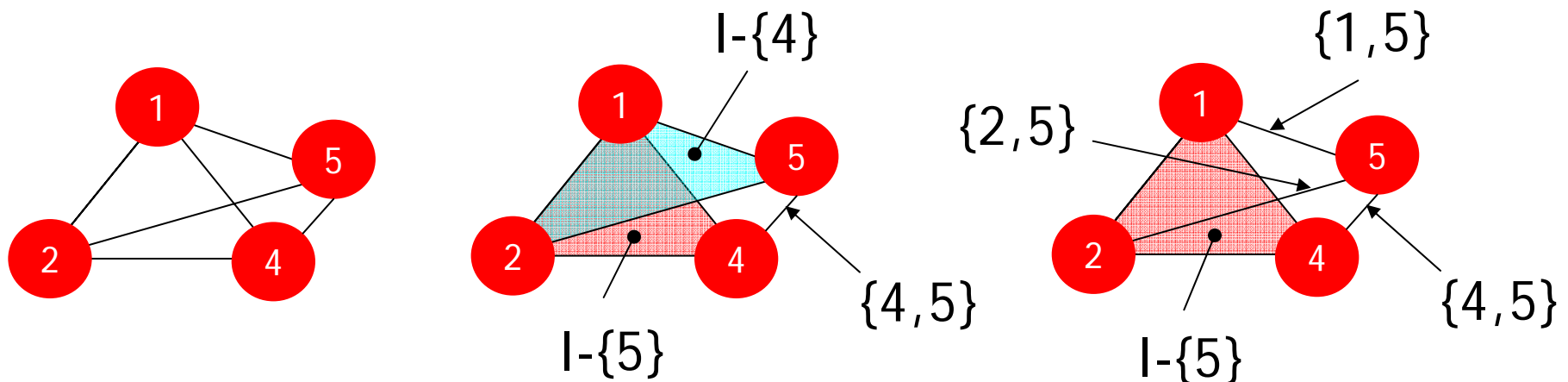
$$\mathcal{J}_3(I) = \bigotimes_{\forall \{x, y\} \subseteq I} \mathcal{J}_3(\{x, y\})$$

1. Dynamic programming

- The optimal substructure appears in the theorem due to homogeneousness

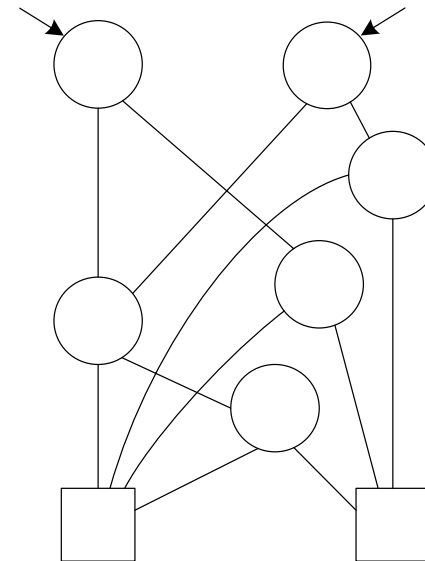
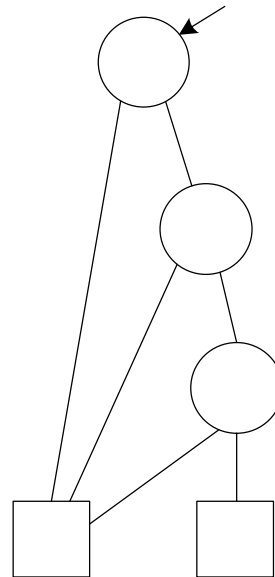
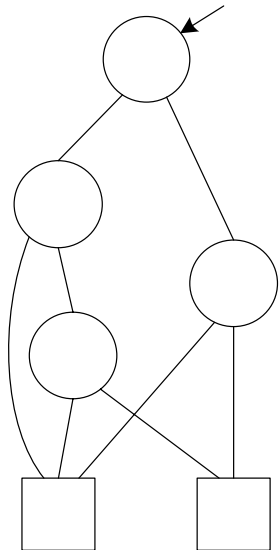
2. Implement the operator \star using ZBDDs

- Type 3, $I = \{1, 2, 4, 5\}$



- $\mathcal{J}_3(\{1, 2, 4, 5\}) = \mathcal{J}_3(\{1, 2\}) \otimes \mathcal{J}_3(\{1, 4\}) \otimes \mathcal{J}_3(\{1, 5\}) \otimes \mathcal{J}_3(\{2, 4\}) \otimes \mathcal{J}_3(\{2, 5\}) \otimes \mathcal{J}_3(\{4, 5\})$
- $\mathcal{J}_3(\{1, 2, 4, 5\}) = \mathcal{J}_3(\{1, 2, 4\}) \otimes \mathcal{J}_3(\{1, 2, 5\}) \otimes \mathcal{J}_3(\{4, 5\})$
- $\mathcal{J}_3(\{1, 2, 4, 5\}) = \mathcal{J}_3(\{1, 2, 4\}) \otimes \mathcal{J}_3(\{1, 5\}) \otimes \mathcal{J}_3(\{2, 5\}) \otimes \mathcal{J}_3(\{4, 5\})$

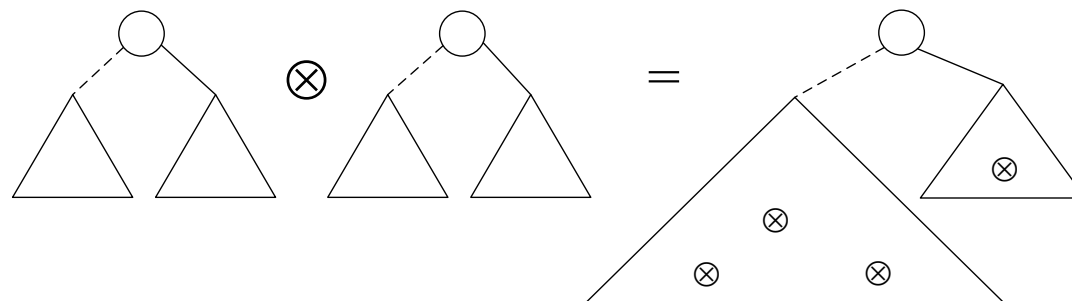
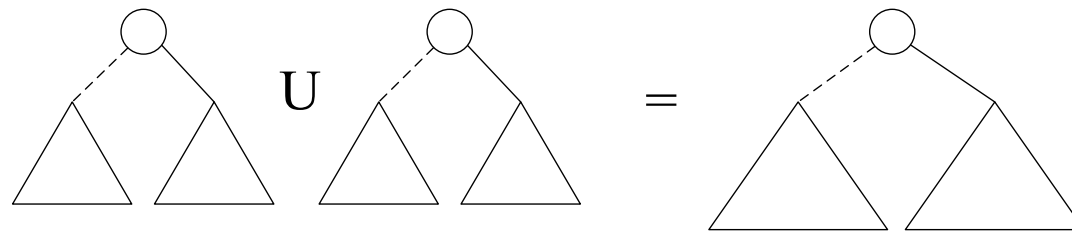
- Use ZBDD
 - First, represent operands in ZBDD
 - Second, manipulate them directly in ZBDD



$\{(1, 4), (3, 5)\}$

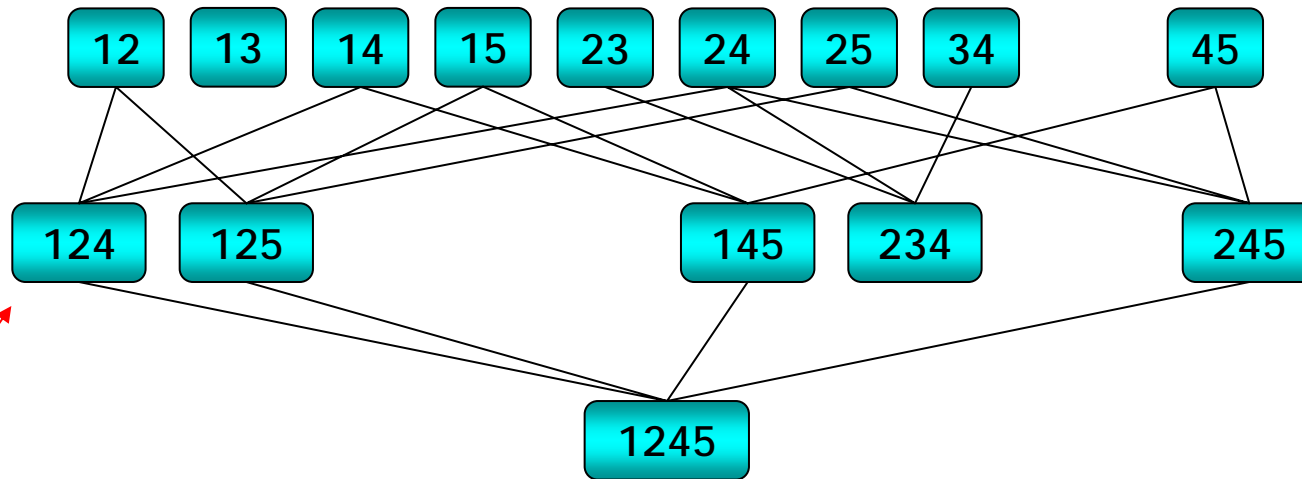
$\{\{3, 4, 5\}\}$

- Idea: recursive decomposition
 - If $P = P_0 \oplus P_1$ and $Q = Q_0 \oplus Q_1$
 - Then $P \otimes Q = (P_0 \otimes Q_0) \oplus (P_1 \otimes Q_1)$



x

x

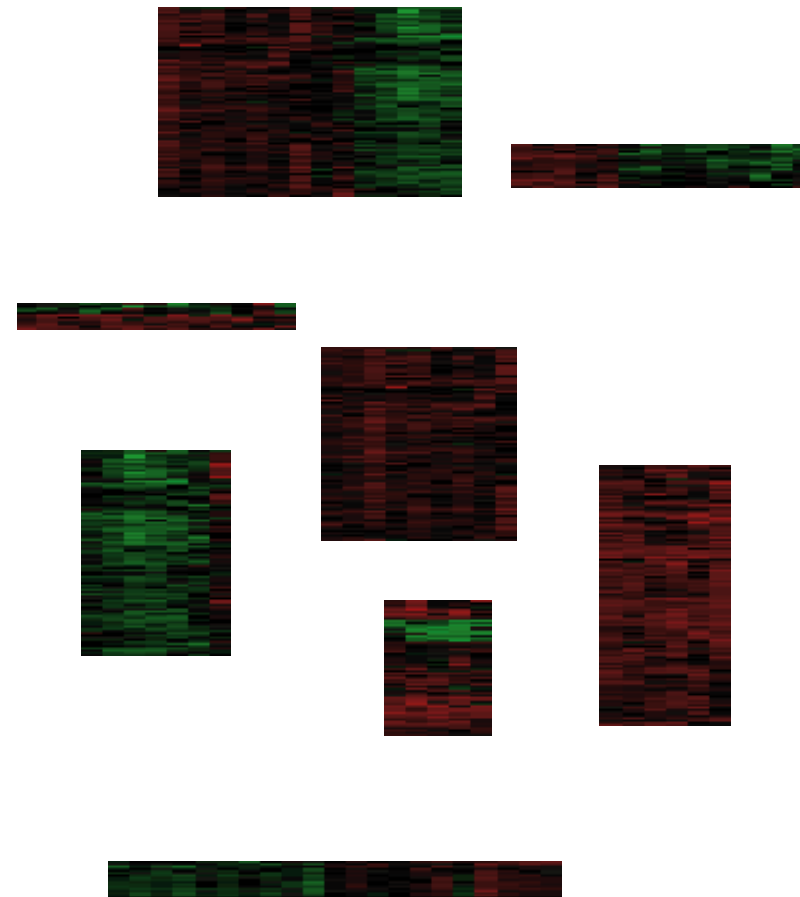
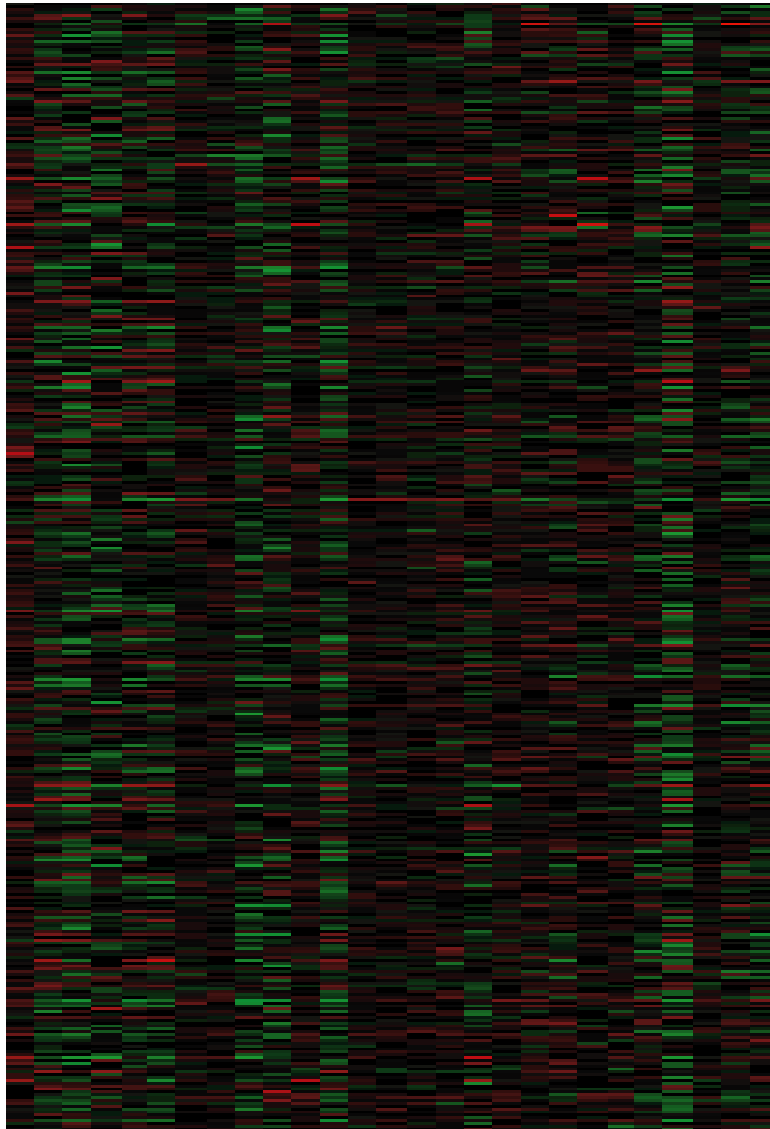


$$\mathcal{I}_3(\{1, 2, 4\}) = \mathcal{I}_3(\{1, 2\}) \otimes \mathcal{I}_3(\{1, 4\}) \otimes \mathcal{I}_3(\{2, 4\})$$

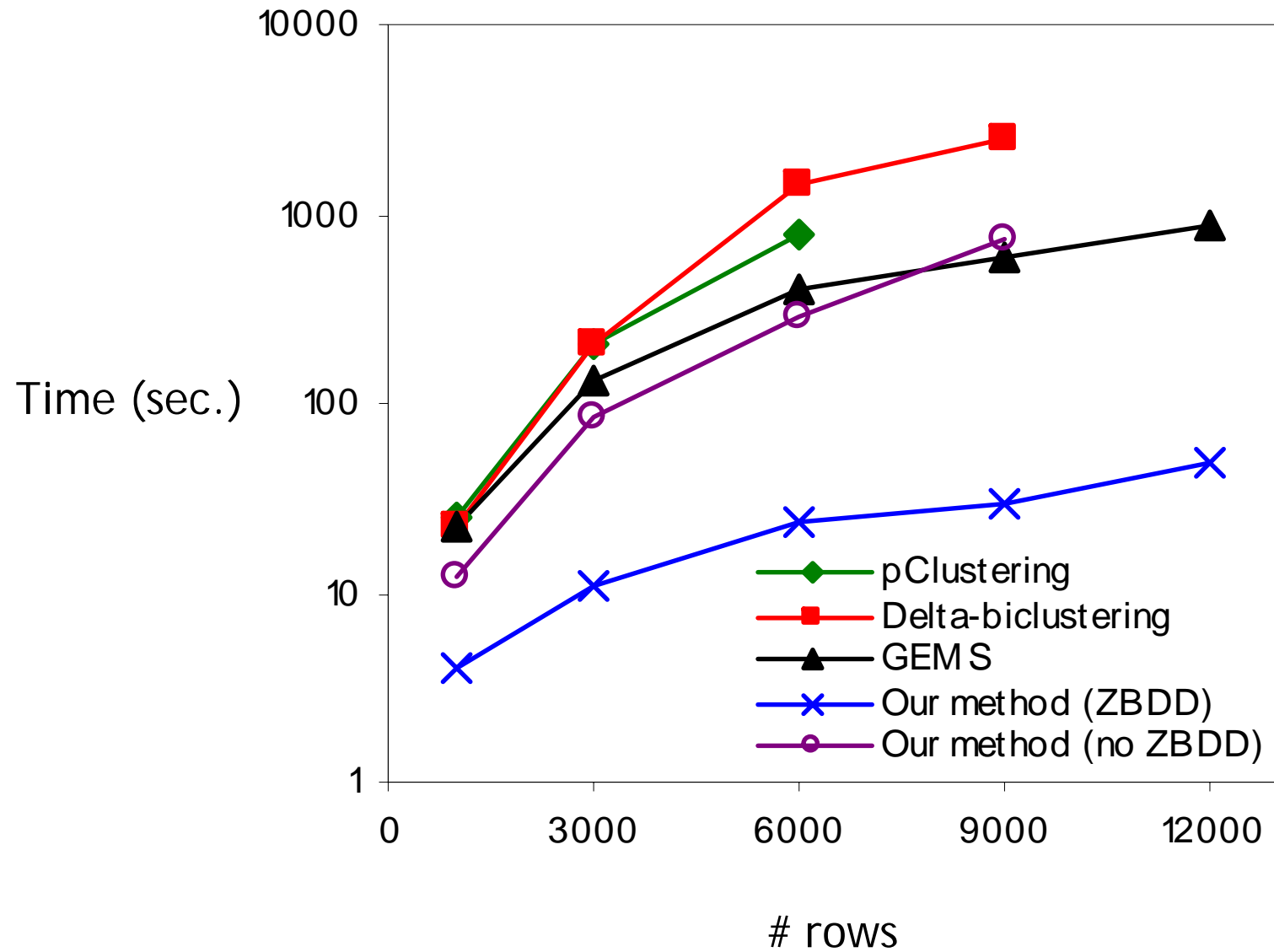
$$\mathcal{I}_3(\{1, 2, 4, 5\}) = \mathcal{I}_3(\{1, 2, 4\}) \otimes \mathcal{I}_3(\{1, 2, 5\}) \otimes \mathcal{I}_3(\{4, 5\})$$

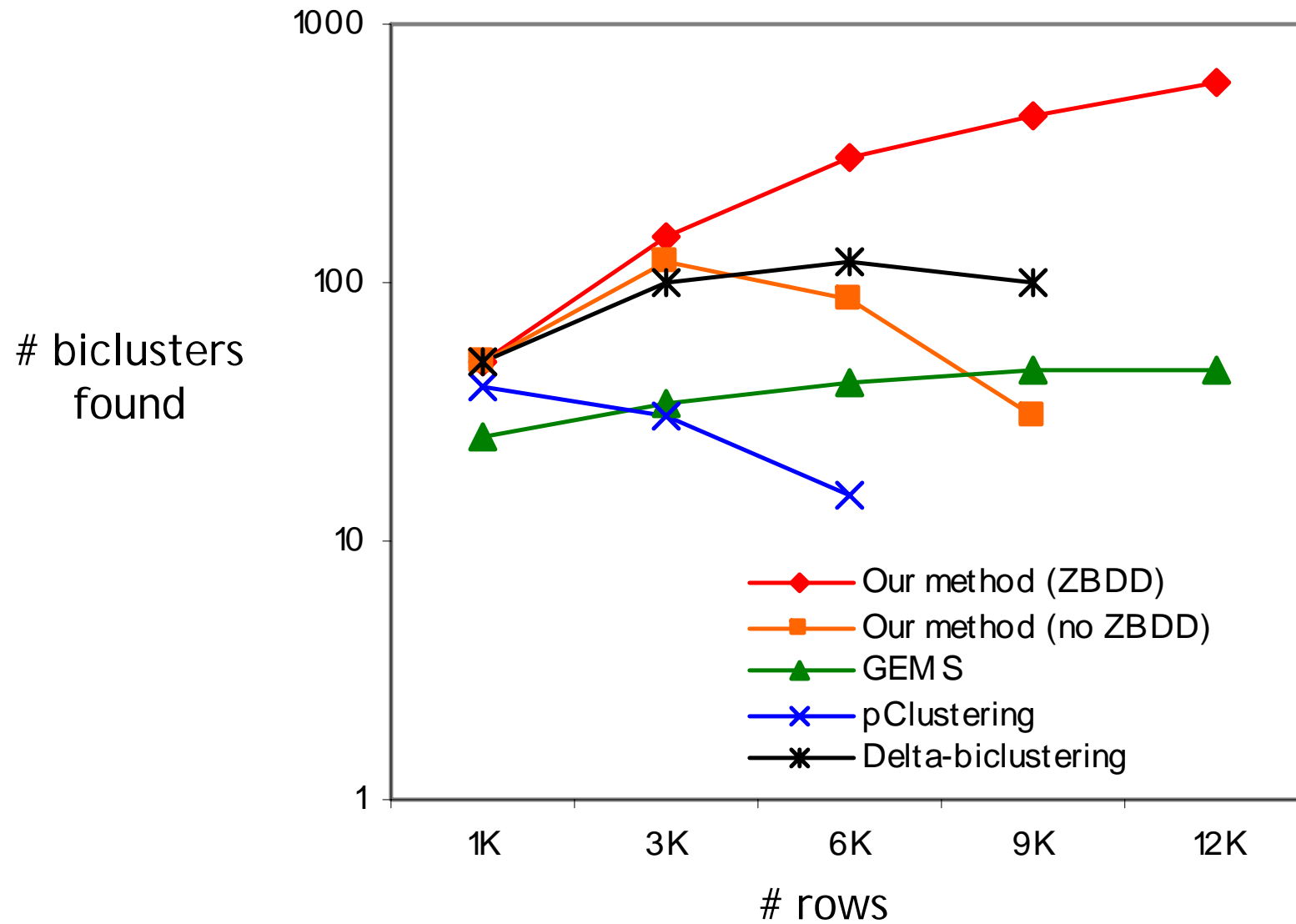
- Introduction
- Problem formulation
- Algorithm description
- **Applications**
 - DNA microarray analysis
 - Finding regulatory modules
 - Correlating genes with clinical parameters

DNA Microarray

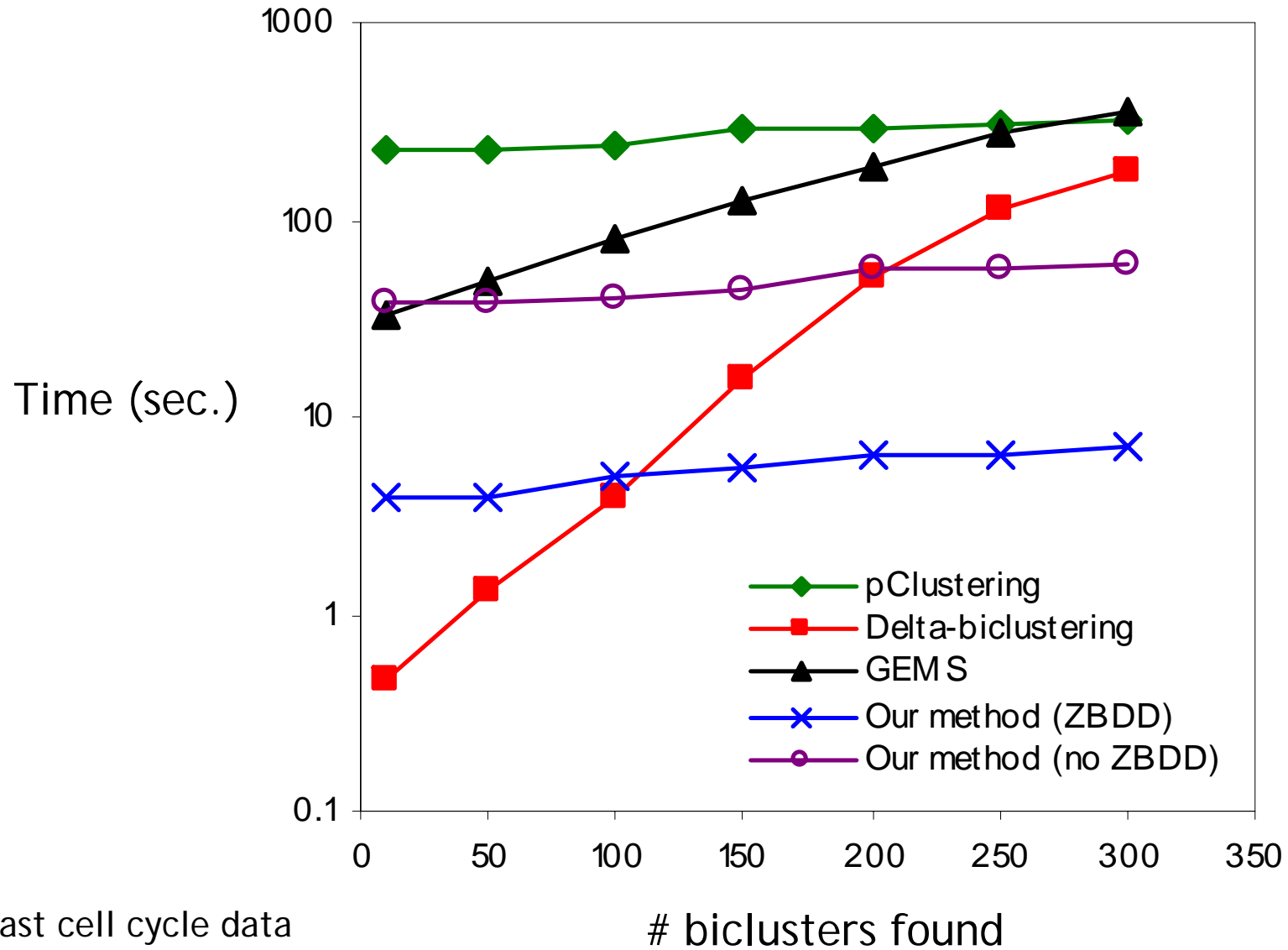


Renal cell carcinoma data (Higgins et al., 2003)



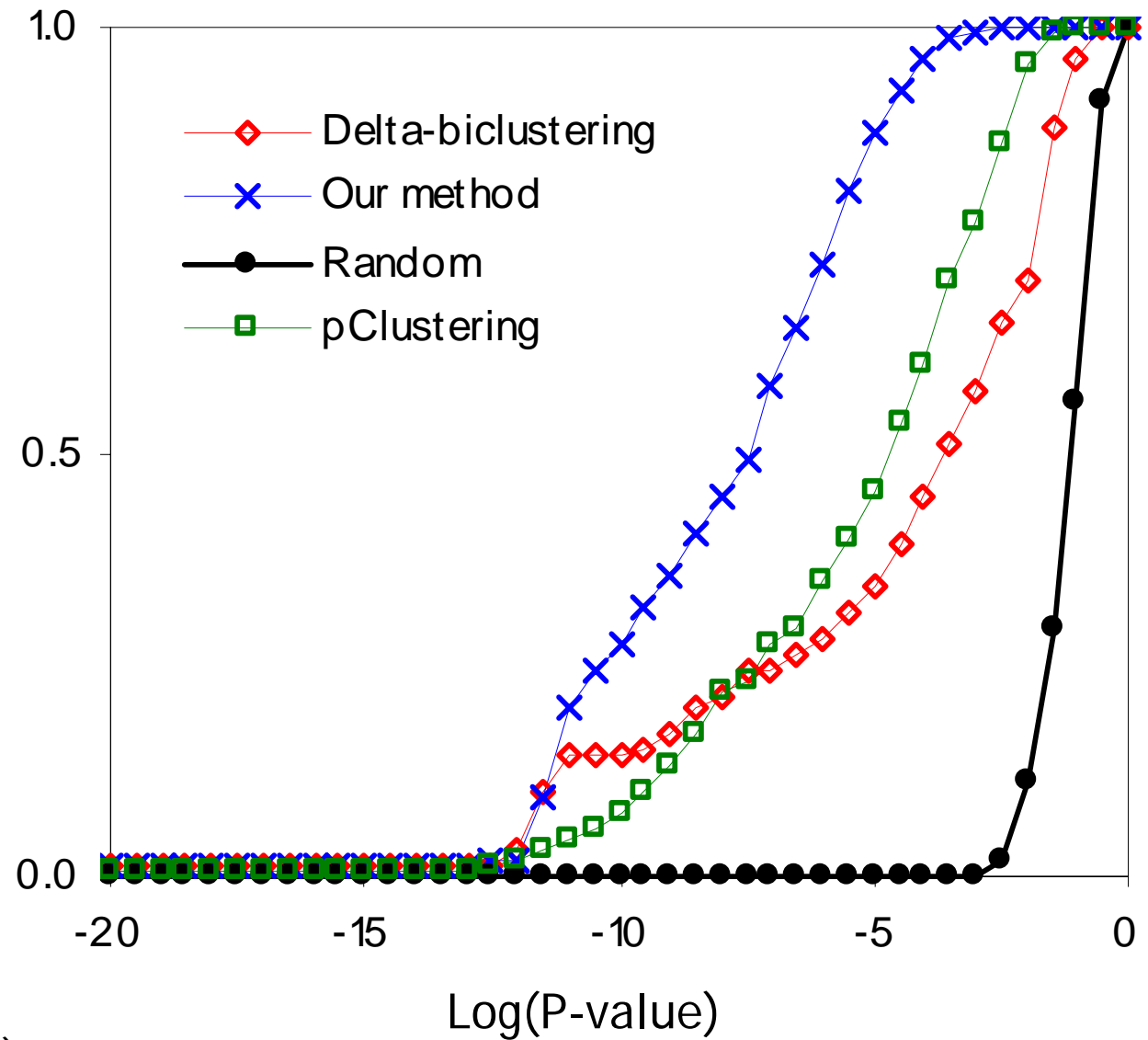


Actual Gene Expression Data

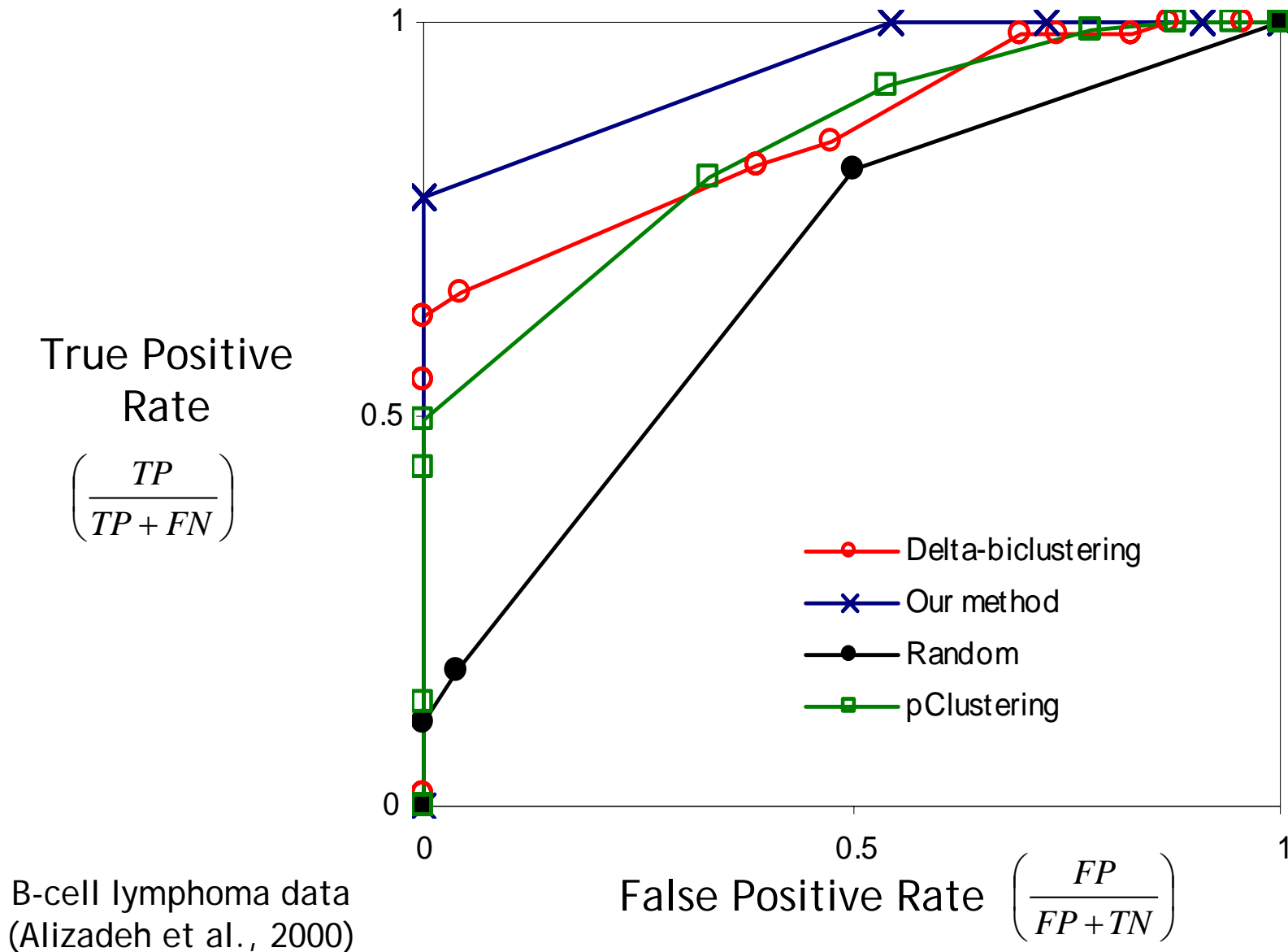


Yeast cell cycle data
(Tavazoie et al., 1999)

Fraction of
biclusters



Yeast cell cycle data
(Tavazoie et al., 1999)



- **Explosion of genomic data**
 - New techniques are emerging
- **Biclustering**
 - Useful but can be computationally expensive
- **BDD**
 - Efficient data structure + algorithms for BF
- **Our biclustering algorithm**
 - Leveraged by ZBDD
 - Exact and scalable algorithm
- **Various applications**

- S. Yoon, C. Nardini, L. Benini and G. De Micheli. "Discovering Coherent Biclusters from Gene Expression Data Using Zero-suppressed Binary Decision Diagrams," *IEEE Transactions on Computational Biology and Bioinformatics*, to appear.